

Fig. 1

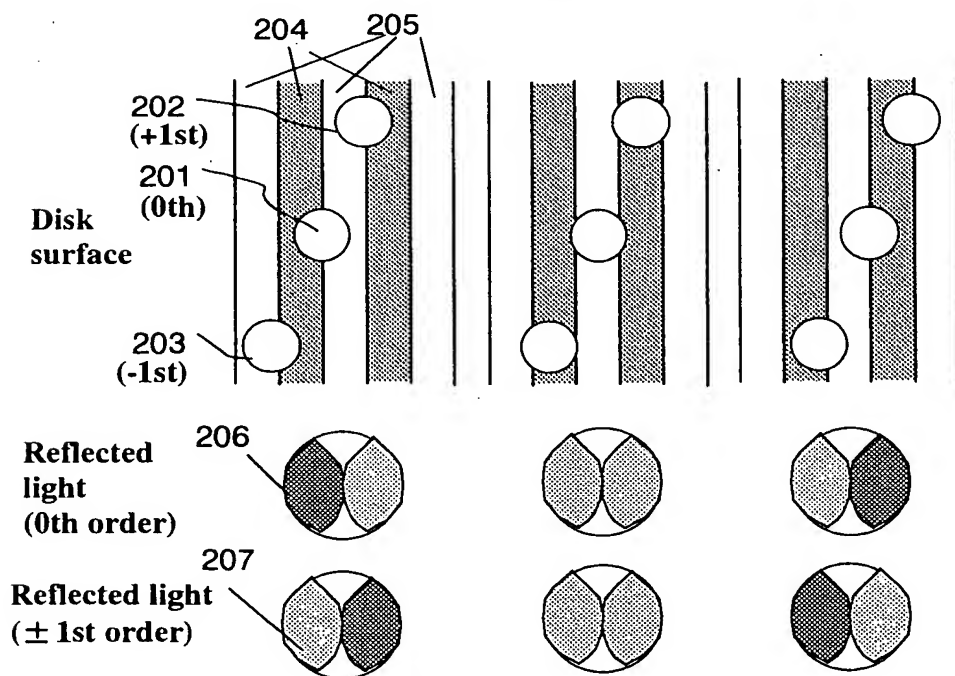


Fig. 2

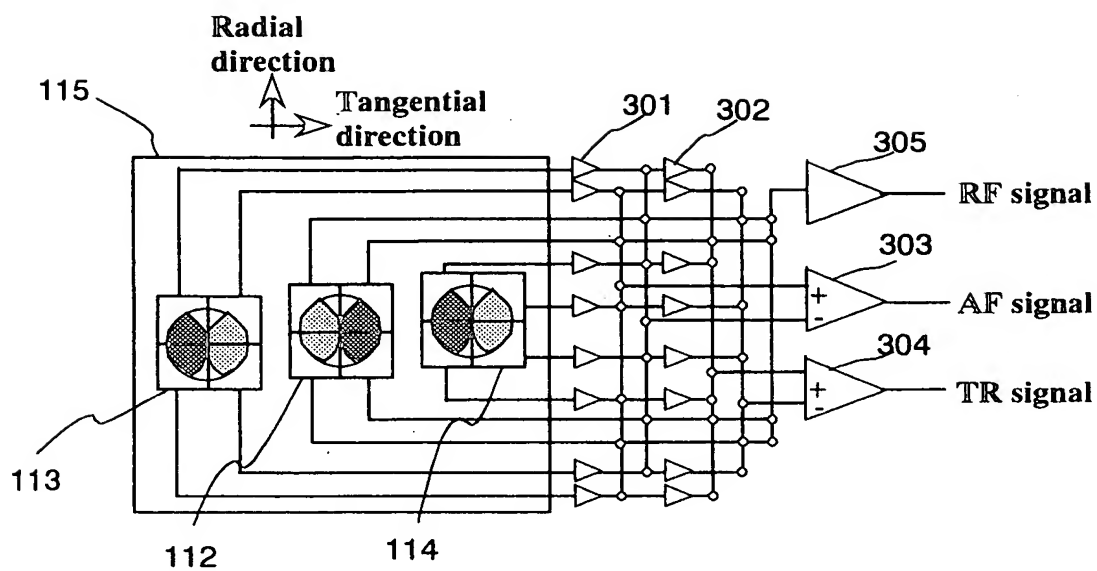


Fig. 3

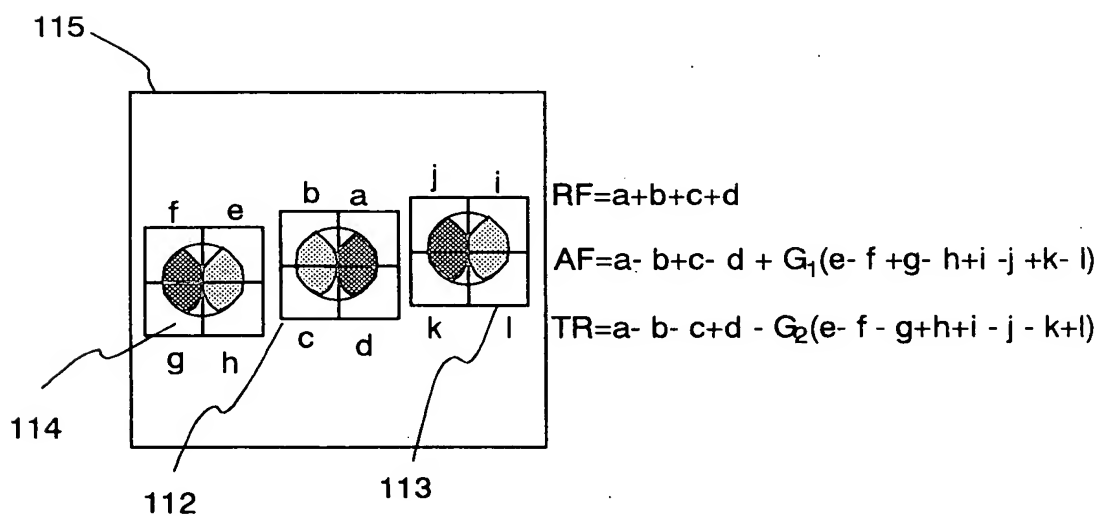


Fig. 4

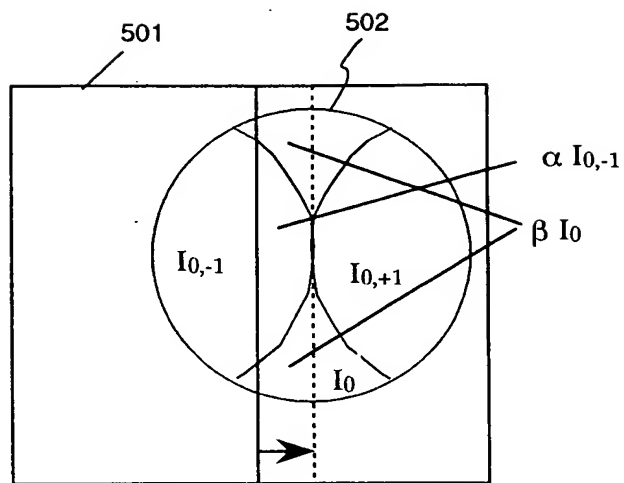


Fig. 5

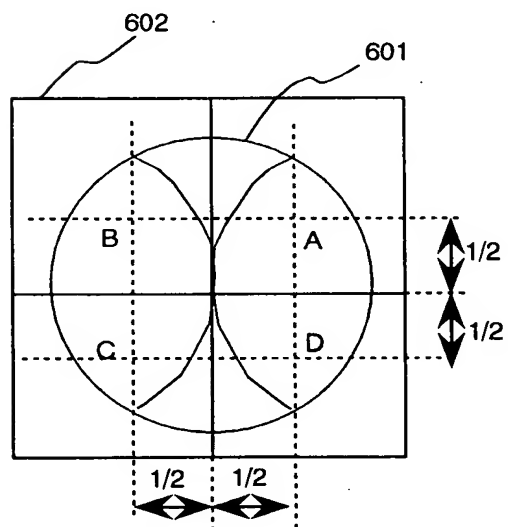


Fig. 6

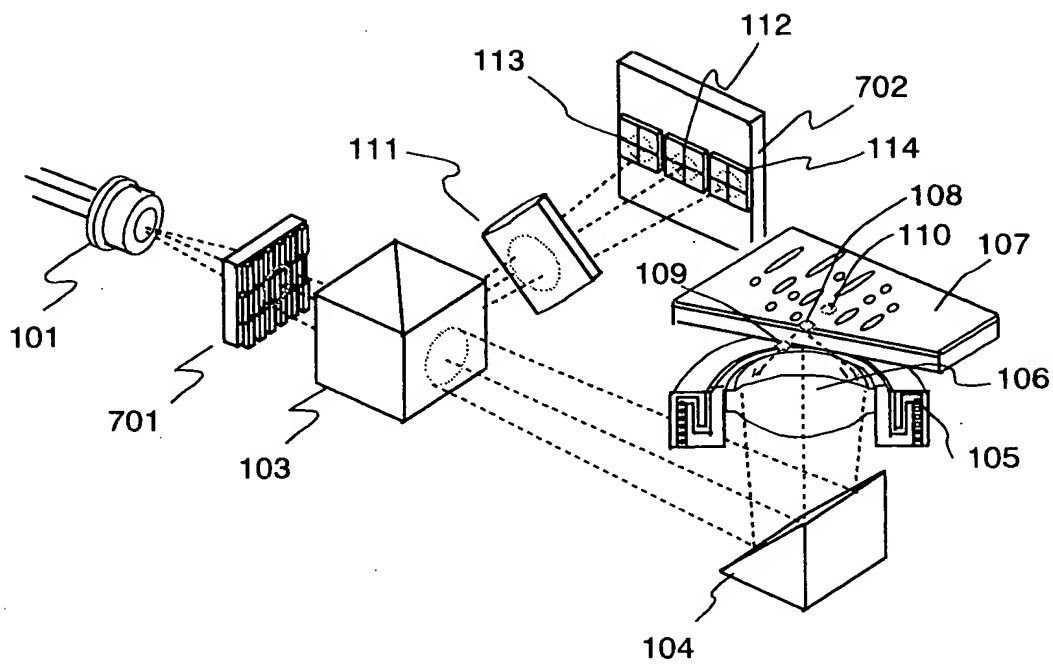


Fig. 7

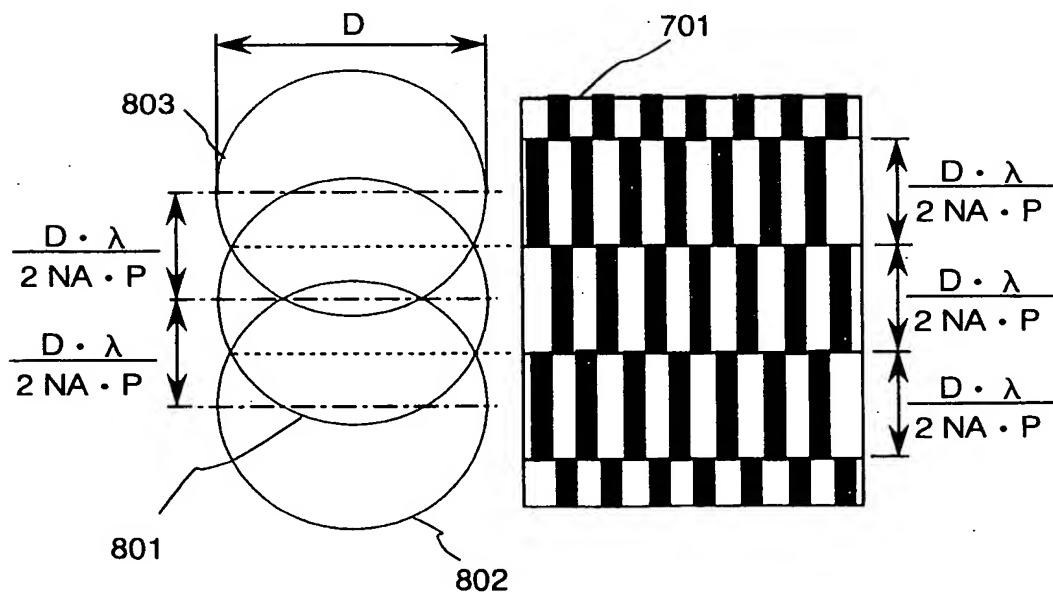


Fig.8

FIG. 9

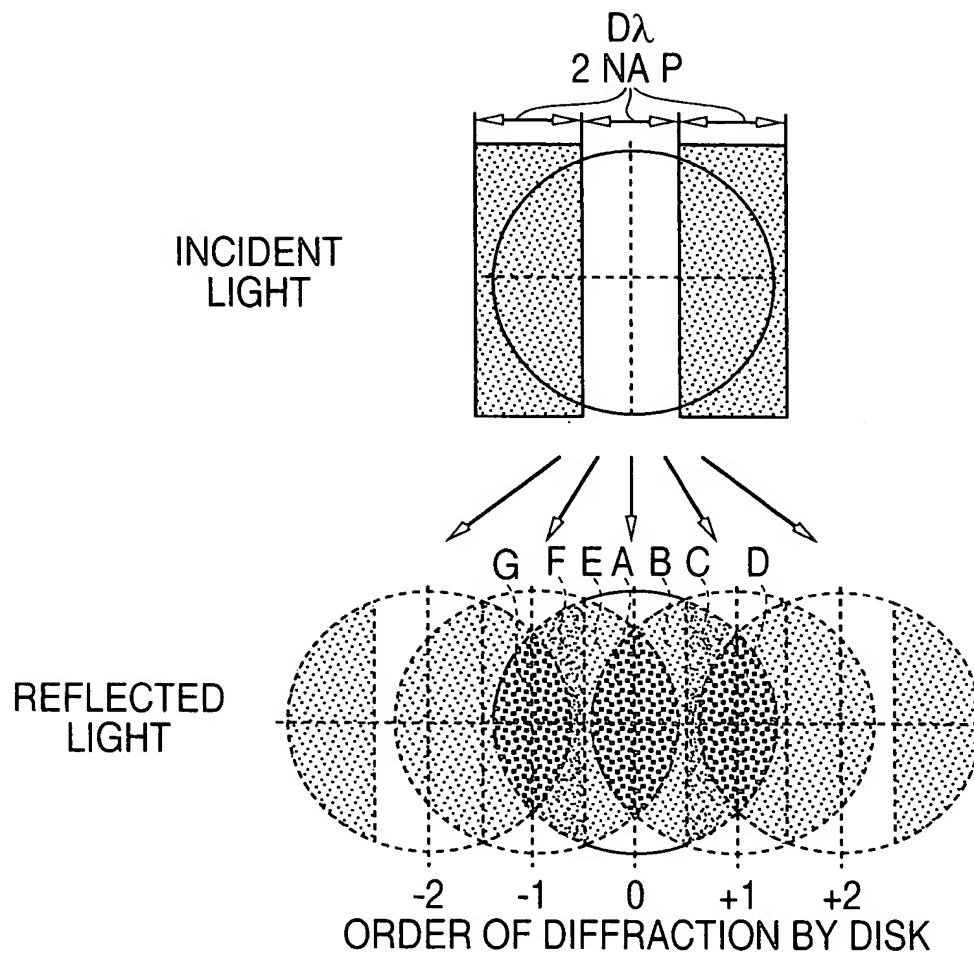


FIG. 10

CHANGES OF PHASE DIFFERENCE OF INTERFERENCE BY PHASE FILTER

INTERFERRING DIFFRACTION ORDER		REGION						
		a	b	c	d	e	f	g
0	-2	-	-	-	-	-	-	0
	-1	π	-	-	-	π	π	π
	1	π	π	π	π	-	-	-
	2	-	-	-	0	-	-	-
-1	-2	-	-	-	-	-	-	π
	1	0	-	-	-	-	-	-
1	2	-	-	-	π	-	-	-

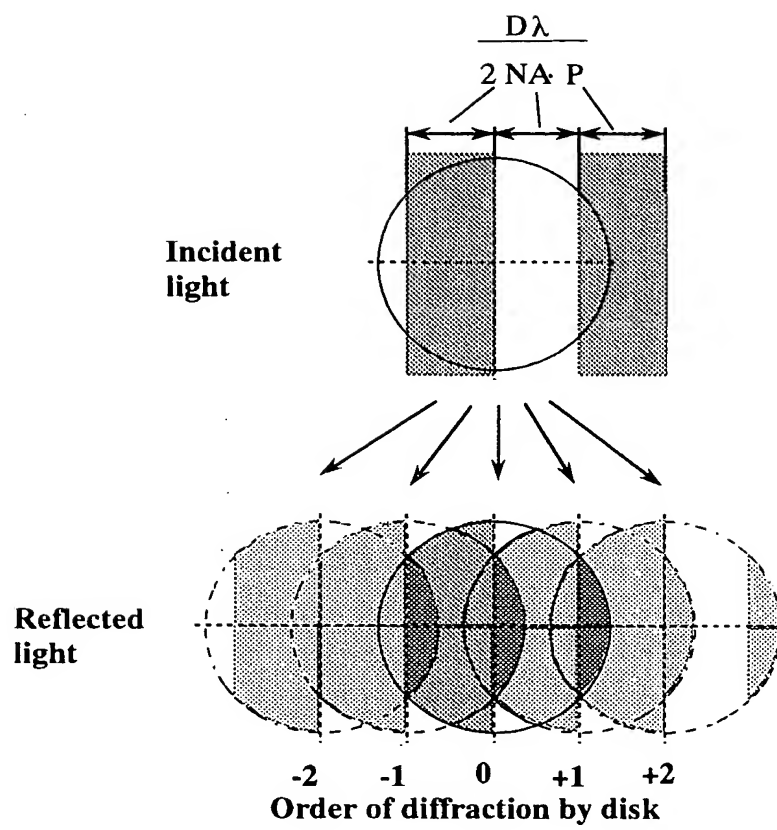


Fig. 11

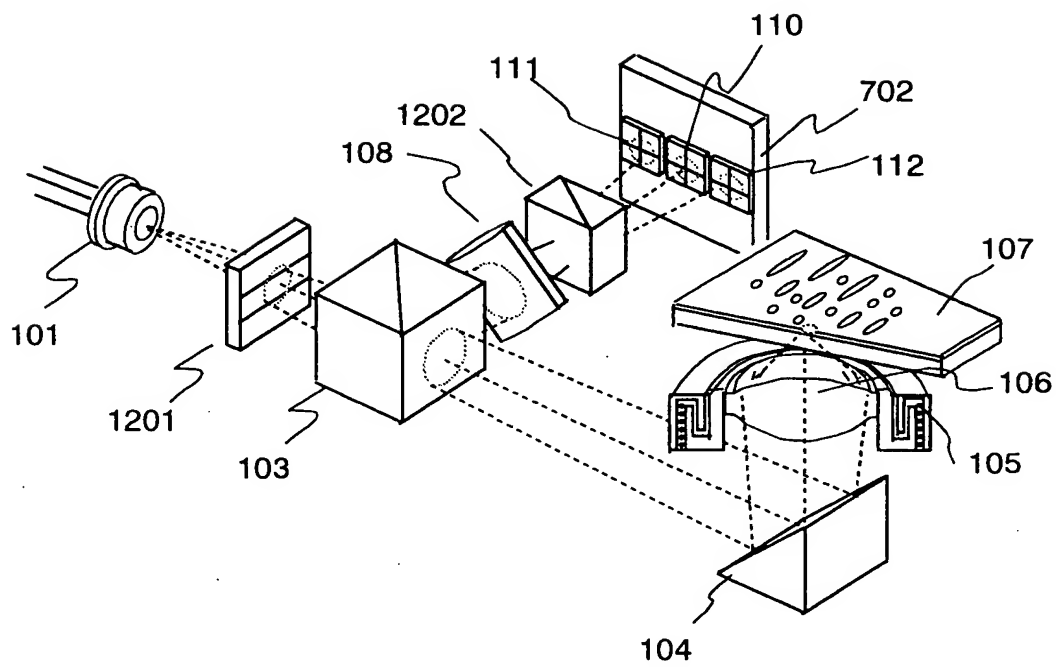


Fig. 12

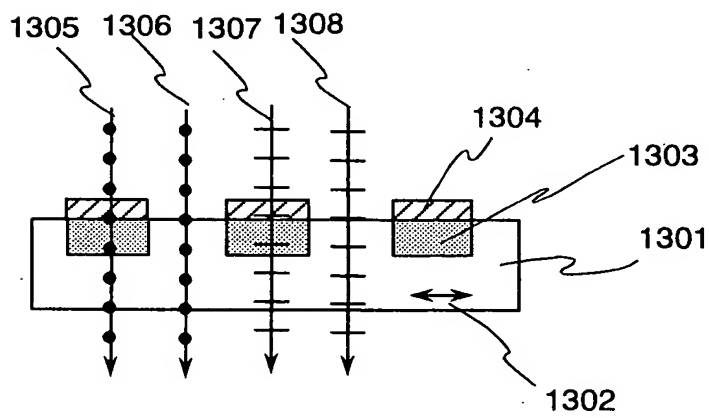


Fig. 13

FIG. 14

NA:0.6, WAVELENGTH:0.66 μm , TRACK PITCH:1.48 μm
 DISK:LAND AND GROOVE, ASTIGMATISM:0.2 λ (-45°),
 SPHERICAL ABERRATION:-0.47 λ ,
 DETECTOR DEVIATION:5 μm (DISK RADIAL DIRECTION)
 FOCAL LENGTH OF DETECTION LENS:22.5mm,
 ASTIGMATIC DISTANCE IN DETECTION OPTICS:0.9mm

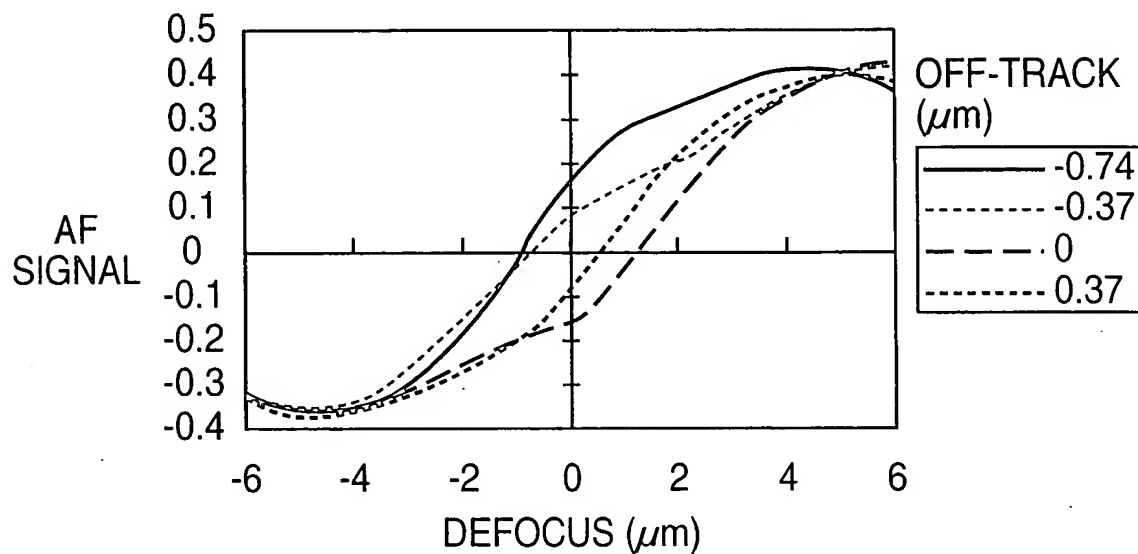
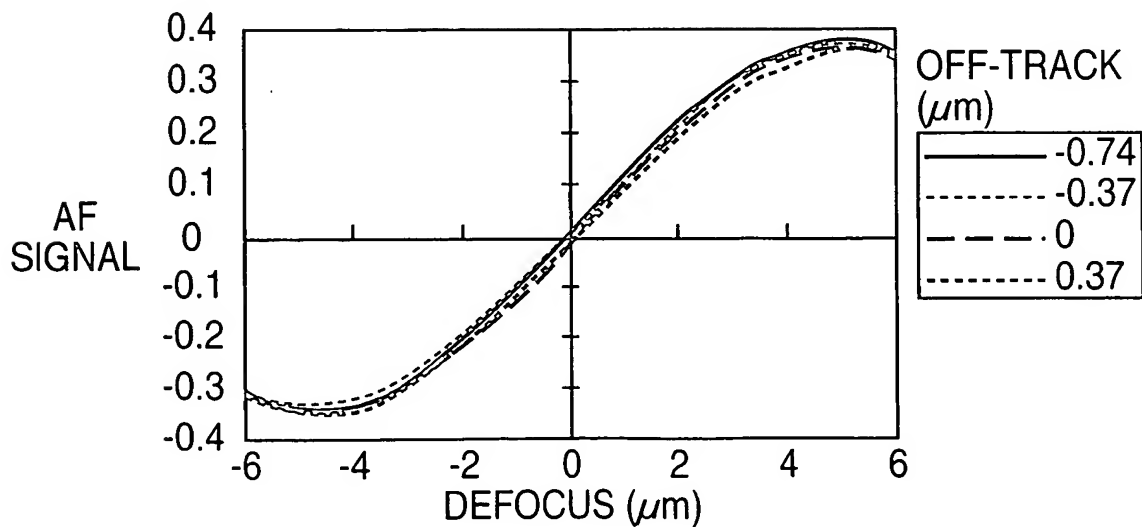


FIG. 15



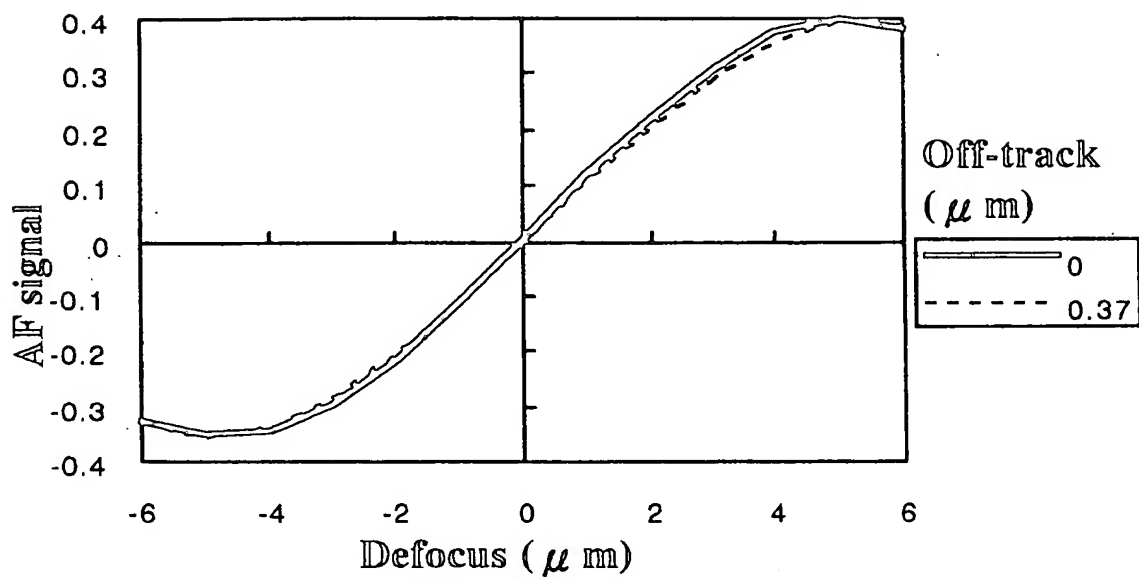


Fig. 16

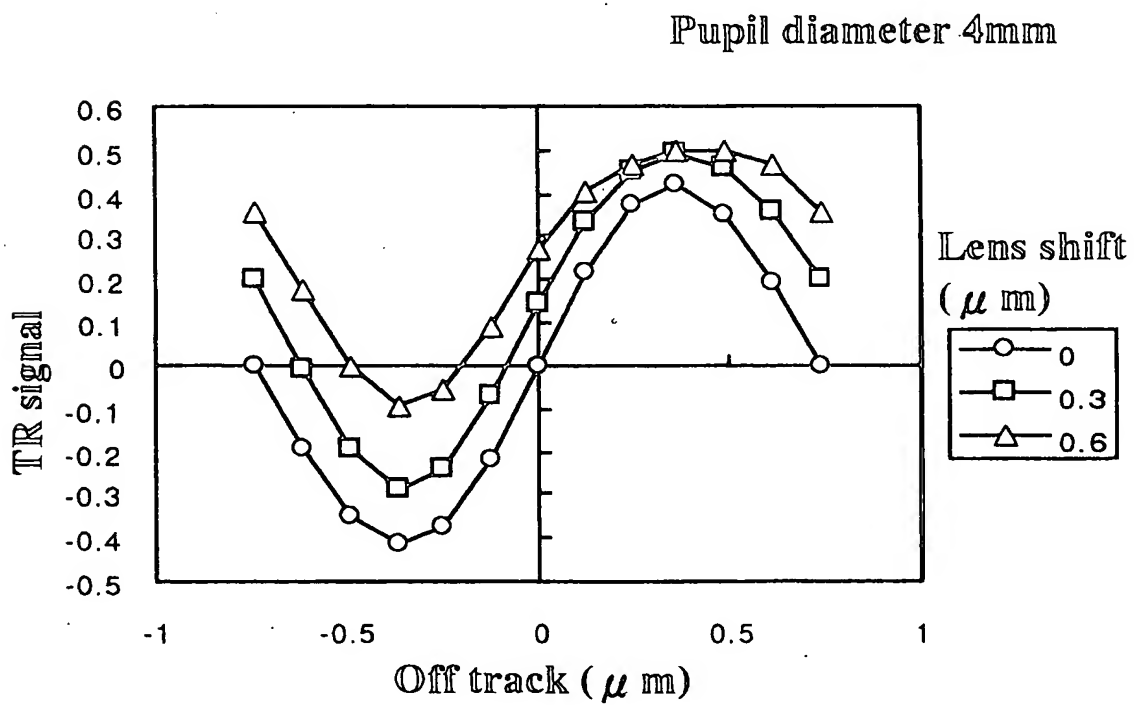


Fig. 17

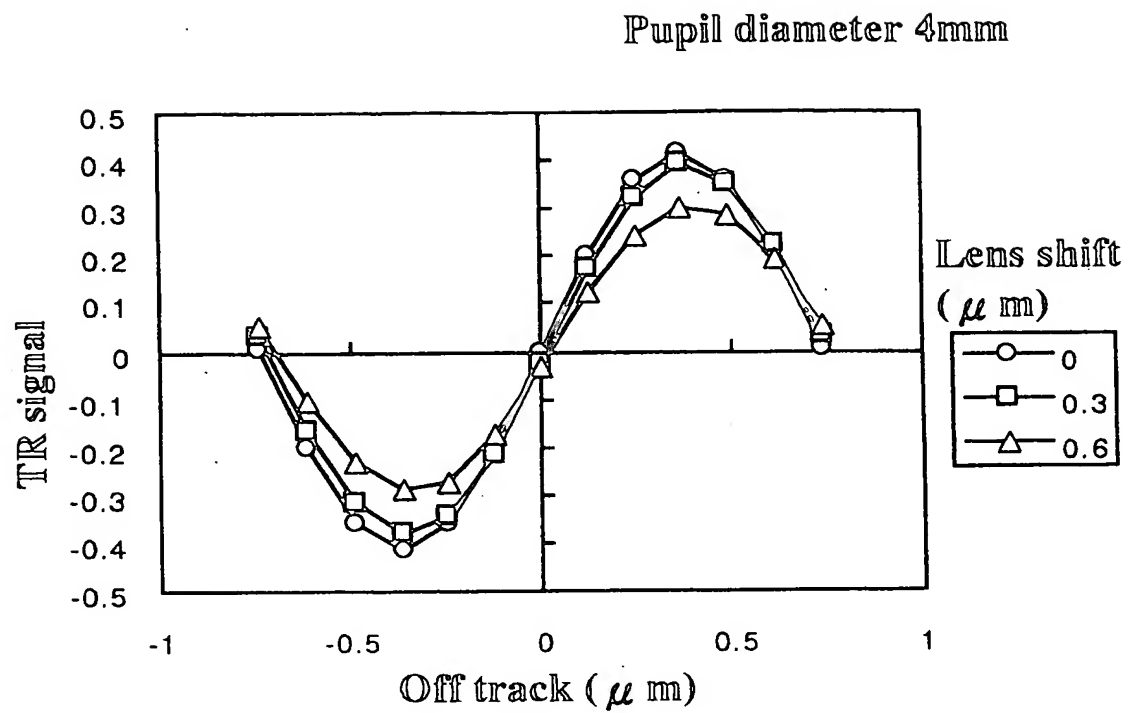


Fig. 18

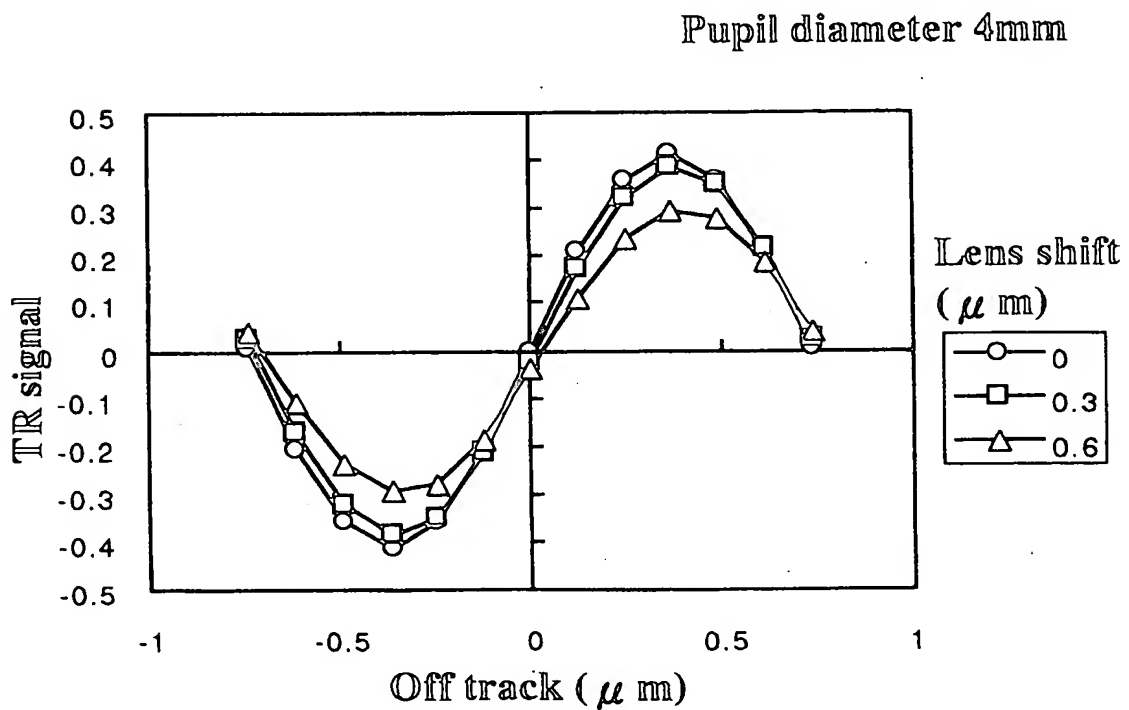


Fig. 19

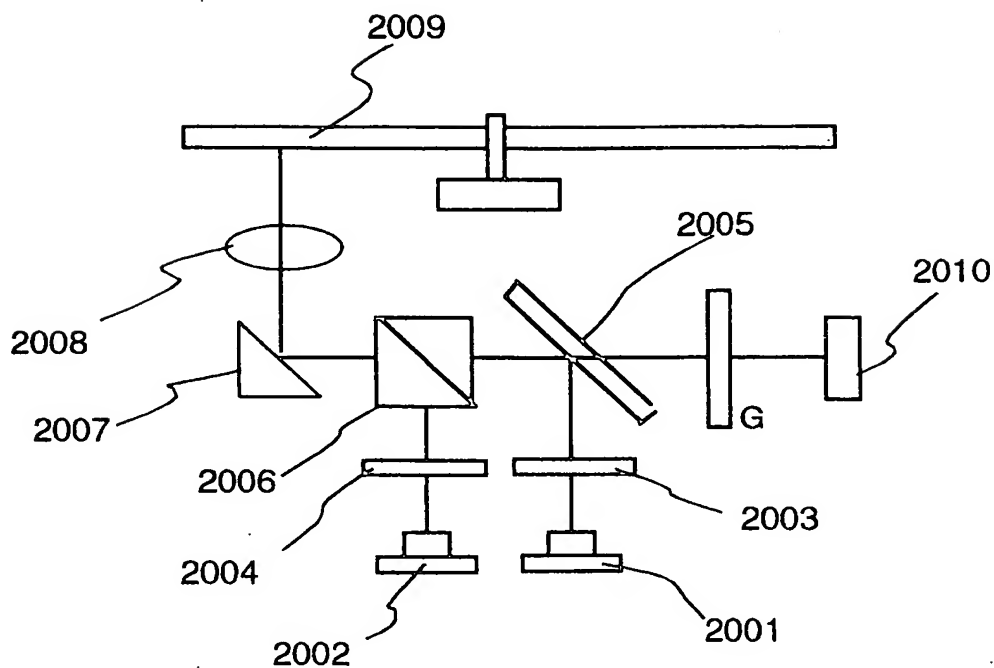


Fig. 20

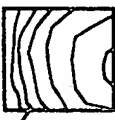
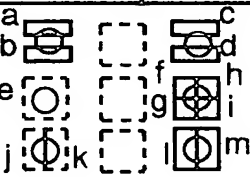
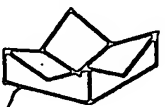
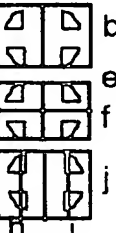
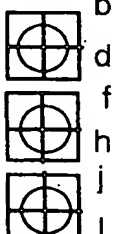
AF signal	G (in Fig.20)	Detector pattern	Operation method
Beam size detection	 2101	 Front focus Back focus	$AF = a + b - c - d$ $PP = f + g - h - i - \alpha (l + m)$ $DPD = f + i - h - g$ $RF = e + f + g + h + i$ $3S-TR = c + d - l - m$ $(\alpha : \text{constant})$
Double knife edge	 2102	 Front focus Back focus	$AF = g - h - i + j$ $PP = \alpha (a - b) - (c + d - e - f)$ $DPD = c - d - e + f$ $RF = c + d + e + f$ $3S-TR = a + b - g - h - i - j$ $(\alpha : \text{constant})$
Astigmatism	No	 Front focus Back focus	$AF = e + h - f - g + a + d - b - c$ $PP = \alpha (a + b - c - d) - (e + f - g - h)$ $DPD = e + h - f - g$ $RF = e + f + g + h$ $3S-TR = a + b + c + d - i - j - k - l$ $(\alpha : \text{constant})$

Fig. 21

FIG. 22

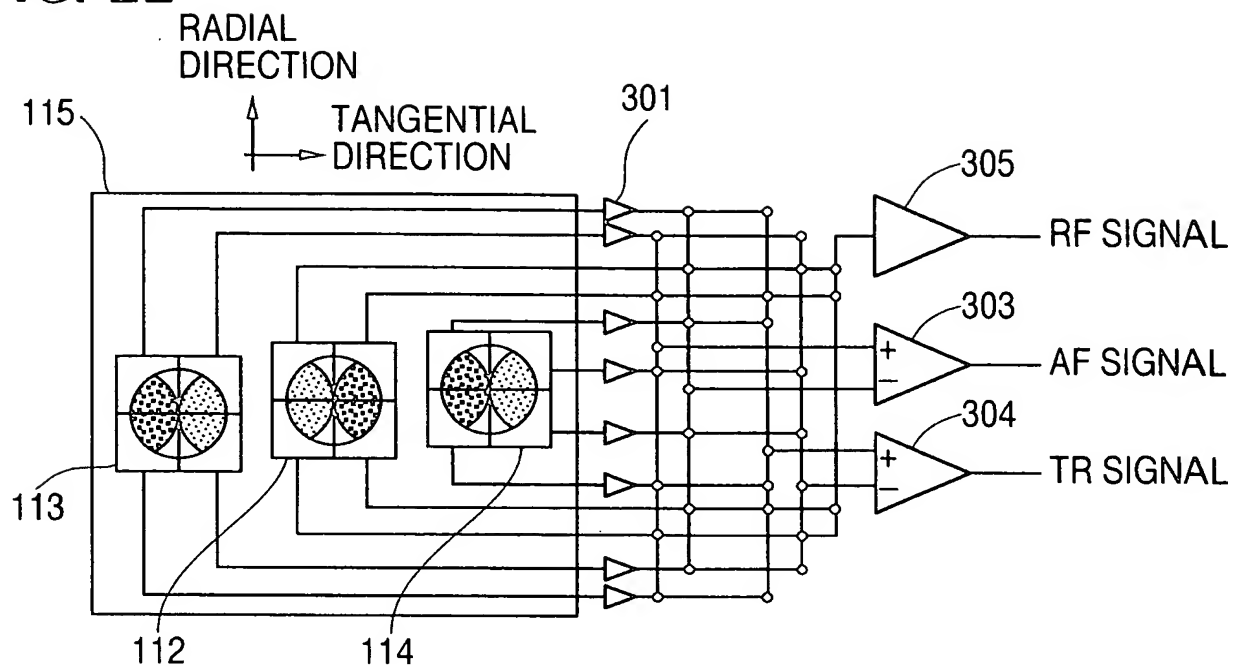


FIG. 23

